

MATHEMATICS

ON ELFVING'S PROBLEM OF IMBEDDING A TIME-DISCRETE MARKOV CHAIN IN A TIME-CONTINUOUS ONE FOR FINITELY MANY STATES. II

BY

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1. The problem, considered in the preceding note (RUNNENBURG [1]), of finding a domain H_n to which the eigenvalues of a matrix of transition probabilities of a continuous parameter Markov chain must necessarily belong, is solved there by using a result in the corresponding problem for discrete parameter Markov chains, obtained by DMITRIEV and DYNKIN [2] and KARPELEWITSCH [3]. For a detailed statement of the problem we refer to [1].

In this note we want to show that the domain H_n can be found by using only the characterization of a Markov matrix given by (1) below.

We use the fact that a Markov-chain on a finite set consisting of n states A_1, A_2, \dots, A_n , induces an abelian semi-group G of real linear transformations on an R_n : with the Markov matrix (p_{jk}) (where $p_{jk} = P\{x_{n+1} = A_k | x_n = A_j\}$) corresponds the linear transformation π defined by

$$\pi e_j = (p_{j1}, p_{j2}, \dots, p_{jn}),$$

where e_j is the j 'th unit vector.

A necessary and sufficient condition that the matrix of a given linear transformation φ is a Markov matrix is

$$(1) \quad \varphi W \subset W,$$

where W is the set of all probability distributions on $\{A_1, A_2, \dots, A_n\}$

$$(2) \quad W = \{x | x = (\xi_1, \xi_2, \dots, \xi_n); \forall_j \xi_j \geq 0; \sum_{j=1}^n \xi_j = 1\}.$$

2. Now let G be a continuous one-parameter abelian semi-group of linear transformations satisfying (1) (ι is the identical transformation on R_n)

$$G = \{\varphi_t | t \in (0, \infty); \forall_t^{(0, \infty)} \varphi_t W \subset W; \forall_t^{(0, \infty)} \forall_s^{(0, \infty)} \varphi_t \varphi_s = \varphi_{t+s}; \lim_{t \downarrow 0} \varphi_t = \iota\}.$$

It is well-known (cf. e.g. FRÉCHET [4]) that under these conditions the eigenvalues of φ_t are $1, \lambda_1^t, \lambda_2^t, \dots, \lambda_m^t$ ($m \leq n-1$), where $1, \lambda_1, \lambda_2, \dots, \lambda_m$ are

eigenvalues of φ_1 , for some choice of the arguments of $\lambda_1, \dots, \lambda_m$. Moreover there is at least one vector $p \in W$, which is invariant under G .

Let $\lambda = \varrho e^{i\psi}$ ($0 \leq \varrho \leq 1$) be an eigenvalue of φ_1 . We suppose that ψ is chosen in such a way that $\varrho^t e^{it\psi}$ is, for all $t > 0$, an eigenvalue of φ_t . We shall show below that

$$(A) \quad \varrho \leq e^{-\psi_0 \operatorname{tg} \pi/}$$

holds, where

$$\psi_0 = \min \{ \psi_0', 2\pi - \psi_0' \} \text{ and } \psi_0' = \psi - [\psi/2\pi] 2\pi,$$

i.e. ψ_0 is the minimum of all non-negative arguments of λ and $\bar{\lambda}$. It is easy to verify that the set of all complex numbers satisfying (A) is equal to the set H_n defined by (7) in [1]. Therefore (A) is equivalent to (6) in [1]. Furthermore (A) is trivially satisfied for $\psi = 0$ (for then $\psi_0 = 0$ also) and for $\varrho = 0$. Therefore we suppose henceforward $\psi \neq 0$ and $\varrho \neq 0$. As changing the unit of time amounts to multiplying ψ by a positive number we can always choose this unit in such a way that $\psi \neq 0$ entails $\lambda \notin R$ (R is the set of real numbers). Finally we assume $n \geq 3$.

Let

$$z_0 = x_0 + iy_0,$$

where x_0 and y_0 are real vectors, be an eigenvector of φ_1 belonging to the eigenvalue λ . As $\lambda \notin R$, it follows that x_0 and y_0 are independent. Then the two-dimensional subspace V spanned by x_0 and y_0

$$V = \{ u | u = \alpha x_0 + \beta y_0; \alpha, \beta \text{ real} \}$$

is invariant under G , and the movement induced by G in V is easily seen to be described by the equations

$$(3) \quad \begin{cases} \varphi_t x_0 = \varrho^t (x_0 \cos t\psi - y_0 \sin t\psi), \\ \varphi_t y_0 = \varrho^t (x_0 \sin t\psi + y_0 \cos t\psi). \end{cases}$$

Introducing

$$W_0 = \{ x | x \in W; \mathcal{A}_j \xi_j = 0 \},$$

$$U = W \cap (p + V) \quad ,$$

$$U_0 = W_0 \cap (p + V) \quad ,$$

the condition (1) together with the invariance of p and V yields

$$(4) \quad V_t^{(0, \infty)} \varphi_t U \subset U.$$

As U is a closed convex polygon¹⁾ in the plane $p + V$ and U_0 its boundary

¹⁾ It might seem that this statement is false for $n = 3$. However in that case our hypothesis $\lambda \notin R$ entails that 1 is the only real eigenvalue of φ_t (and hence of the adjoint transformation). Therefore $\{x | \xi_1 + \xi_2 + \xi_3 = 0\}$ is the only possible real invariant two-dimensional subspace and thus $V = \{x | \xi_1 + \xi_2 + \xi_3 = 0\}$, implying $W \subset p + V$, whence $U = W$ and $U_0 = W_0$.

the condition (4) is satisfied if and only if

$$(5) \quad V_t^{(0, \infty)} \varphi_t U_0 \subset U$$

is satisfied.

To derive a geometric condition equivalent with (5), consider a vector $w \in U_0$. The curve $\{\varphi_t w | t > 0\}$ must, on account of (5), be in U . Hence a vector v_1 tangent to $^1) \{\varphi_t w | t \geq 0\}$ in w must point from w to the interior of U . To make this condition more precise consider a vector v_2 pointing from w along U_0 in such a way that v_1 lies inside the angle $^2)$ formed by $p-w$ and v_2 .

If now we define

$$(6) \quad \theta_w = \angle(p-w, v_1); \theta_{0,w} = \angle(p-w, v_2),$$

then it is easily seen that (5) is satisfied if and only if

$$(7) \quad \forall_{w \in U_0} \theta_w \leq \theta_{0,w}$$

is true.

3. It does not seem possible to deduce useful results directly from (7), as θ_w is in general a complicated expression depending on w . The only case in which θ_w is independent of w obtains when $|x_0| = |y_0|$ and the inner product $(x_0, y_0) = 0$, which will be shown below. The general case can be reduced to this case by means of the following considerations:

Let σ be a real non-singular linear transformation on R_n . Then the semi-group

$$G^* = \sigma G \sigma^{-1}$$

consists of those linear transformations φ_t^* for which

$$\varphi_t^* = \sigma \varphi_t \sigma^{-1}.$$

These φ_t^* have the same eigenvalues as φ_t and eigenvectors

$$z^* = \sigma z, \text{ with } z^* = x^* + iy^*; x^* = \sigma x; y^* = \sigma y,$$

where $z = x + iy$ is an eigenvector of φ_t .

Application of the transformation σ to $W, p, x_0, y_0, V, U, U_0, v_1, v_2$ yields $W^*, p^*, x_0^*, y_0^*, V^*, U^*, U_0^*, v_1^*, v_2^*$, i.e. $W^* = \sigma W$, etc.

We can now repeat the argument of 2 and arrive at equivalent conclusions. In particular, if we define

$$(6^*) \quad \theta_w^* = \angle(p^* - w, v_1^*); \theta_{0,w}^* = \angle(p^* - w, v_2^*),$$

¹⁾ Where $\varphi_0 \stackrel{\text{df}}{=} \iota$.

²⁾ There is a slight difficulty here on account of the fact that p may be in U_0 . This case does not occur if $\psi \neq 0, \varrho \neq 0$: On account of (3) any vector $w - p$ performs a complete rotation around p in the time interval $(0, 2\pi/\psi]$, and does not vanish in this time interval. Hence (5) and $p \in U_0$ are inconsistent.

then

$$(7^*) \quad \forall_{w \in U_0^*} \theta_w^* \leq \theta_{0,w}^*$$

is equivalent with (7).

In view of the remark at the beginning of this section, we choose σ in such a way that

$$(8) \quad |x_0^*| = |y_0^*| \text{ and } (x_0^*, y_0^*) = 0.$$

Using (8) it is easy to calculate θ_w^* . For an arbitrary $w \in p^* + V^*$ we have

$$(9) \quad w = p^* + \alpha(x_0^* \sin \gamma + y_0^* \cos \gamma) \quad (\alpha, \gamma \text{ real}).$$

Consider $\{\varphi_t w | t \geq 0\}$. A vector tangent to this curve in w is given by

$$(10) \quad v_1^* = \lim_{h \downarrow 0} \frac{\varphi_h^* w - w}{h}.$$

Substitution of (9) and

$$(3^*) \quad \begin{cases} \varphi_t^* x_0^* = \varrho^t(x_0^* \cos t\psi - y_0^* \sin t\psi) \\ \varphi_t^* y_0^* = \varrho^t(x_0^* \sin t\psi + y_0^* \cos t\psi) \end{cases}$$

in (10) gives after some calculation

$$(11) \quad v_1^* = -\alpha A[x_0^* \sin(\gamma - \chi) + y_0^* \cos(\gamma - \chi)],$$

where

$$(12) \quad A^2 = \psi^2 + \log^2 \varrho; \quad 0 < \chi < \pi \text{ and } \operatorname{ctn} \chi = -\psi^{-1} \log \varrho.$$

Then, using (8), (11) and (9), it follows that

$$(13) \quad \cos \theta_w^* = \frac{(p^* - w, v_1^*)}{|p^* - w| \cdot |v_1^*|} = \cos \chi,$$

and hence (as θ_w^* and χ are both in $[0, \pi]$)

$$(14) \quad \theta_w^* = \chi.$$

We thus see that θ_w^* is indeed independent of w . Our condition (7*) yields

$$(15) \quad \chi \leq \inf_{w \in U_0^*} \theta_{0,w}^*.$$

4. As σ is non-singular, W^* is like W an $(n-1)$ -simplex. Hence U_0^* , being the boundary of the intersection of W^* with a plane that has at least one point (namely p^*) in common with W^* , is a convex polygon with at most n vertices, say a_1, a_2, \dots, a_n . It is then easy to see, that the infimum in the right-hand side of (15) is reached if w is in one of the vertices of U_0^* . Therefore, if we introduce ¹⁾

$$\left. \begin{aligned} \alpha_j &= \angle p^* a_j a_{j+1} \\ \alpha_{j'} &= \angle p^* a_j a_{j-1} \end{aligned} \right\} \quad (j=1, 2, \dots, n; \text{ indices taken mod } n),$$

¹⁾ For any three vectors a, b and c we use the following notation:

$$\angle abc \stackrel{\text{df}}{=} \angle (a - b, c - b).$$

then

$$(16) \quad \inf_{w \in U_0^*} \theta_{0,w}^* = \min \alpha_j \text{ or } \min \alpha_j',$$

depending on whether the sense of rotation in $p^* + V^*$ given by p^*, w, v_1^* in that order is the same as the rotational sense given by a_1, a_2, \dots, a_n or that given by a_n, a_{n-1}, \dots, a_1 respectively.

In 5 we shall give a proof of the fact that

$$(17) \quad \min_j \alpha_j \leq \frac{n-2}{2n} \pi; \quad \min_j \alpha_j' \leq \frac{n-2}{2n} \pi,$$

with equality in at least one of these two relations if and only if the polygon under consideration is regular and p^* its centre.

Combination of (15), (16) and (17) yields

$$\chi \leq \frac{n-2}{2n} \pi,$$

from which it follows that

$$(18) \quad \varrho \leq e^{-\psi \operatorname{tg} \pi/n}.$$

Now ψ is of the form $\psi_0' + 2k\pi$ with $0 \leq \psi_0' < 2\pi$ and k an integer. As $\bar{\lambda}$ is also an eigenvalue of φ_1 , we may conclude

$$(19) \quad \mathcal{A}_k \varrho \leq e^{-(\psi_0' + 2k\pi) \operatorname{tg} \pi/n} \text{ and } \varrho \leq e^{-(\psi_0' - 2k\pi) \operatorname{tg} \pi/n}.$$

If we put

$$\psi_0 = \min \{\psi_0', 2\pi - \psi_0'\},$$

than either $\psi_0' + 2k\pi \geq \psi_0$ or $-\psi_0' - 2k\pi \geq \psi_0$, hence (A) holds for all eigenvalues λ of φ_1 for which $\psi \neq 0$, $\varrho \neq 0$, and therefore for all eigenvalues of φ_1 (cf. the remarks at the beginning of section 2).

5. It remains to prove (17). To this purpose suppose, with the notation of section 4

$$(21) \quad \forall_j \alpha_j \geq \frac{n-2}{2n} \pi.$$

Then it is possible to find vectors¹⁾ $p_1 \in \langle p^*, a_1 \rangle$, $p_2 \in \langle p^*, a_2 \rangle$, ..., $p_n \in \langle p^*, a_n \rangle$ in such a way that

$$\angle p^* a_n p_1 = \angle p^* p_1 p_2 = \dots = \angle p^* p_{n-1} p_n = \frac{n-2}{2n} \pi.$$

Then, as $p_n \in \langle p^* a_n \rangle$

$$\frac{|p_n - p^*|}{|a_n - p^*|} \leq 1,$$

¹⁾ We denote by $\langle b_1, b_2, \dots, b_k \rangle$ the closed convex hull of $\{b_1, \dots, b_k\}$:

$$\langle b_1, b_2, \dots, b_k \rangle = \{x | x = \alpha_1 b_1 + \alpha_2 b_2 + \dots + \alpha_k b_k; \forall_j \alpha_j \geq 0; \sum_{j=1}^k \alpha_j = 1\}.$$

with equality if and only if $V_j p_j = a_j$. Introducing $\alpha_j'' = \angle p^* p_j p_{j-1}$ ($j=2, \dots, n$) and $\alpha_1'' = \angle p^* p_1 a_n$, we find

$$1 \geq \frac{|p_n - p^*|}{|a_n - p^*|} = \frac{|p_n - p^*|}{|p_{n-1} - p^*|} \cdot \frac{|p_{n-1} - p^*|}{|p_{n-2} - p^*|} \cdots \frac{|p_1 - p^*|}{|a_n - p^*|} = \prod_{j=1}^n \frac{\sin \frac{n-2}{2n} \pi}{\sin \alpha_j''}.$$

Hence

$$(22) \quad \prod_{j=1}^n \sin \alpha_j'' \geq \sin^n \frac{n-2}{2n} \pi,$$

with equality if and only if $V_j \alpha_j'' = \alpha_j'$.

On the other hand, as the sum of the angles ($n\pi$) of the n triangles $\langle a_n, p_1, p^* \rangle, \langle p_1, p_2, p^* \rangle, \dots, \langle p_{n-1}, p_n, p^* \rangle$ is equal to

$$\sum_{j=1}^n \alpha_j'' + 2\pi + n \cdot \frac{n-2}{2n} \pi,$$

we have

$$\sum_{j=1}^n \alpha_j'' = n\pi - 2\pi - n \cdot \frac{n-2}{2n} \pi = \frac{n-2}{2} \pi.$$

As $-\log \sin x$ is a convex function for $0 < x < \pi$, we have

$$(23) \quad \prod_{j=1}^n \sin \alpha_j'' \leq \sin^n \frac{1}{n} \sum_{j=1}^n \alpha_j'' = \sin^n \frac{n-2}{2n} \pi$$

with equality if and only if

$$V_j \alpha_j'' = \frac{n-2}{2n} \pi.$$

Combination of (22) and (23) yields:

$$(24) \quad V_j \alpha_j' = \alpha_j'' = \frac{n-2}{2n} \pi.$$

We can now repeat this argument, starting from

$$(25) \quad V_j \alpha_j' \geq \frac{n-2}{2n} \pi,$$

which follows from (24). We then arrive at the conclusion

$$(26) \quad V_j \alpha_j = \frac{n-2}{2} \pi.$$

Hence, either of (21) or (25) entails (24) and (26). In other words: Either

$$V_j \alpha_j = \alpha_j' = \frac{n-2}{2n} \pi,$$

in which case $\langle a_1, a_2, \dots, a_n \rangle$ is regular with centre p^* , or

$$\min_j \alpha_j < \frac{n-2}{2n} \pi \text{ and } \min_j \alpha_j' < \frac{n-2}{2n} \pi,$$

which proves (17).

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